MPC3028A
8-Axis Motion Control Card

User's Manual (V1.0)

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Correction record

Version	Record
1.0	MPC3028A compatible with old version MPC3028

Contents

Notes on hardware installation

Please follow step by step as you are installing the control cards.

1. Be sure your system is power off.
2. Be sure your external power supply for the wiring board is power off.
3. Plug your control card in slot, and make sure the golden fingers are put in right contacts.
4. Fasten the screw to fix the card.
5. Connect the cable between the card and wiring board.
6. Connect the external power supply for the wiring board.
7. Recheck everything is OK before system power on.
8. External power on.

Congratulation! You have it.

For more detail of step by step installation guide, please refer the file “installation.pdf “ on the CD come with the product or register as a member of our user’s club at:

http://automation.com.tw/

to download the complementary documents.

1. Forward

Thank you for your selection of 8-axis motion control card. This card adopt the ASIC chip with complex motion functions including point to point, linear and circular interpolation, linear and s-curve acceleration/deceleration and several miscellaneous functions. Dll's of various functions will save you a lot of time in the motion related projects.

Our other motion control products:

MPC3024A 4 axes linear/circular/point to point (standard function) motion control card (PCI bus)

MPC3024AC 4-axis linear/circular/point to point (standard function) motion control card with Pulse referenced PI closed loop control (PCI bus)

MPC3034A 4 axes linear/circular/point to point (advanced function) motion control card (PCI bus)

MPC3042A 2 axes linear/circular/point to point (standard function) motion control card with Pulse Referenced PI Control (PCI bus)

MPC3042AL 2 axes linear/circular/point to point (standard function) motion control card (PCI bus)

MPC3035A 4 axes linear/circular/point to point (standard function) motion control card with advanced encoder counter function / with 2 8bit DA's motion control card (PCI bus)

MPC3035AL 4 axes linear/circular/point to point (standard function) motion control card with advanced encoder counter function motion control card (PCI bus)

Any comment is welcome,
please visit our website
http://www.automation.com.tw/
http://www.automation-js.com/ for the up to date information.

2. Features

2.1 Main card

2.1.1 8-axis servo/stepping motor control
2.1.2 8 28-bit up/down counter for incremental encoder
2.1.3 4 28-bit up/down counter for pulse handler input
2.1.4 Pulse output rate up to 6.55MHz
2.1.5 Pulse output options : OUT/DIR,CW/CCW
2.1.6 2~8 axes linear interpolation
2.1.7 Circular interpolation of the same chip: any 2 axes
2.1.8 S curve or T curve acceleration / deceleration in interpolation and positioning
2.1.9 Continuous interpolation
2.1.10 Speed change on the fly
2.1.11 Synchronized start motion
2.1.12 Position latch function
2.1.13 Simultaneously start/stop on multi-axes
2.1.14 Programmable interrupt conditions
2.1.15 Backlash compensation
2.1.16 Pulse handler function
2.1.17 Software limit switches protection
2.1.18 2 nibble configurable TTL I/O
2.1.19 Motion parameters change on the fly
2.1.20 8 isolated digital I/P
2.1.21 8 isolated digital O/P

2.2 Din rail mounted wiring board

2.2.1 JS51050 dummy wiring board for JM3 pulse handler interface
2.2.2 ADP3024DIN wiring board for JF1,2,5,6 motion control interface
2.2.3 ADP9201DIN for JM6 isolated digital I/O interface

3. Specifications

3.1 MPC3028A Main card

Motion

3.1.1 Max pulse rate — 6,553,500 pps

3.1.2 Pulse output mode — Single phase: CLOCK,DIR

3.1.3 Dual phase — CW, CCW

3.1.4 Acceleration / Deceleration mode — linear ,S-curve mode

3.1.5 Homing mode — 14 types

3.1.6 Encoder up/down counter — 8 28bit counter

3.1.7 Pulse Handle up/down counter — 4 28 bit counter

3.1.8 Linear interpolation — any 2 up to 4 axis (of the same chip)

3.1.9 Circular interpolation — any 2 axes (of the same chip)

Digital I/O

3.1.10 Motion specific input — SRDY, ALM, LS+(EL+), LS-(EL-), SD, HOME(ORG), PCS, LTC per axis , EMG per card

3.1.11 Motion specific output — CMP,SVON,ERC,FIN per axis

3.1.12 General input — INP per axis

3.1.13 TTL I/O — 2 nibble configurable TTL I/O

3.1.14 Isolated I/O — 8I/P, 8 O/P

General

3.1.15 Card ID — 16 locations set by rotary switch

3.1.16 Insulation resistance — 100 MΩ (min) at 1000Vdc

3.1.17 Isolation voltage — 2500Vac 1Min

3.1.18 I/O connector — 4 68pin female mini SCSI connector
1 20 pin flat cable
1 25 pin D type connector

3.1.19 External supply — DC 24±4V

3.1.20 Operation temperature — 0 to 70° C

3.1.21 Storage temperature — -20 to 80° C

3.1.22 Operation humidity — 5~95% RH, non-condensing

3.1.23 Dimensions — 175(W) * 122(H) mm , 6.9(W)*4.8(H)in

3.2 Din rail mounted wiring board

ADP3024DIN for JF1,2,5,6 motion control interface

3.2.1 Power Requirement — 24Vdc ± 4Vdc

3.2.2 On Board Build-in s.p.s. — +5Vdc 500mA (max)

3.2.3 General input — 4 with LED indicator

3.2.4 Output capacity — 8 NMOS output, 1A continuous、120Vdc(max)
Option : 8 PMOS output, 1A continuous、24Vdc(max)
Option : 8 Relay output, 3A continuous、250Vac(max)

3.2.5 Connector — 2 68pin mini SCSI female connector for main card connection

3.2.6 Specific servo control connectors — 4 D-type 26p (1 per axis)

3.2.7 Operation temperature — 0 to 70° C

3.2.8 Operation humidity — RH5~95%, non-condensed

3.2.9 Dimension — ADP3024DIN(N) : 121(W) * 204(L) *47(H)mm;
4.8(W)*8.1(L)*1.9(H)in
ADP3024DIN(P) / (R) : 121(W) * 204(L) *45(H)mm
4.8(W)*8.1(L)*1.8(H)in

JS51050 for JM3 pulse handler interface

3.2.10 Connection cable — D-type 25P cable to connect main and wiring board

3.2.11 Dimension — 86(W)*79(L)*52(H)mm , 3.4(W)*3.2(L)*2.1(H)in

ADP9201DIN for JM6 isolated digital I/O

3.2.12 Power Requirement — 24Vdc ± 4Vdc

3.2.13 Indicator — 8 input and 8 output LED indicators

3.2.14 Output capacity — 8 relay output, 3A @250Vac , 3A @30Vdc
Option : 8 PMOS output, 1A @24Vdc
Option : 8 SSR output, 2A@250Vac

3.2.15 Connector — 20pin

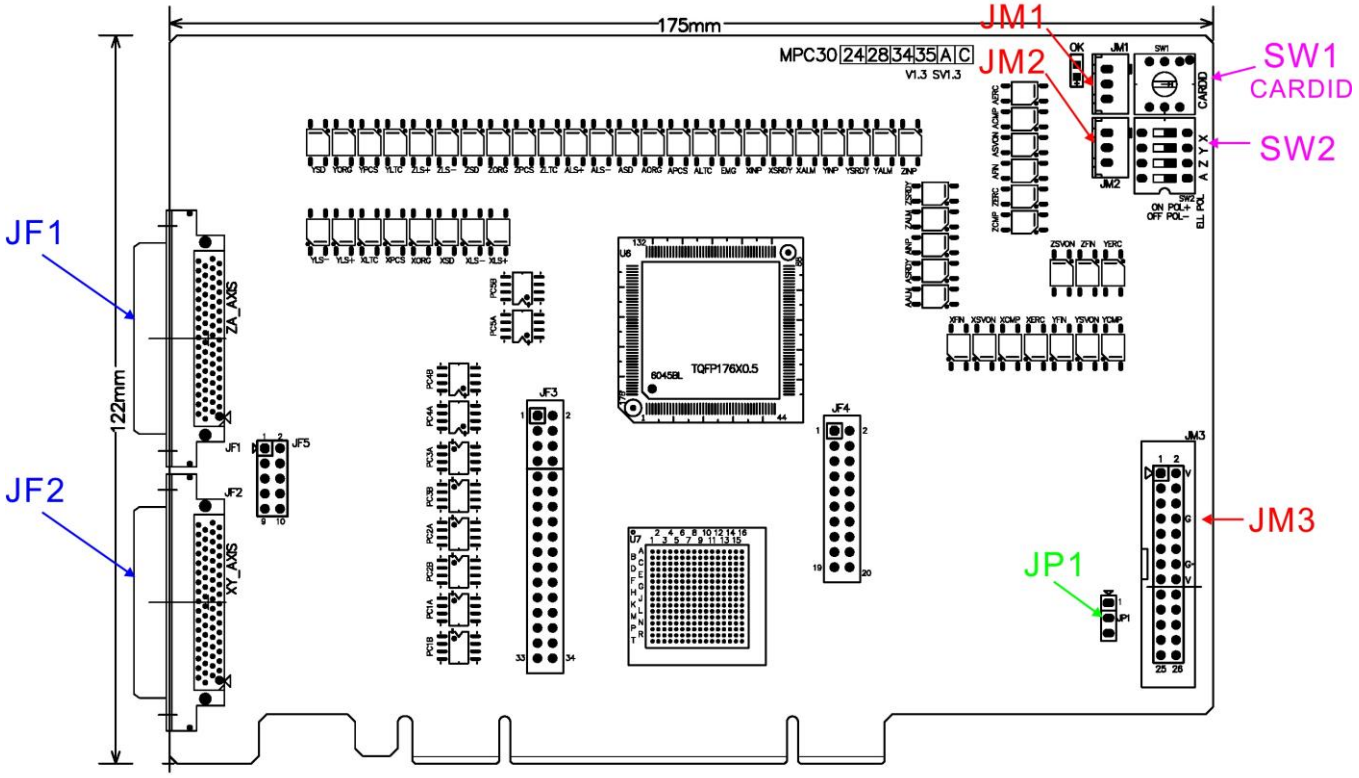
3.2.16 Operation temperature — 0 to 70° C

3.2.17 Operation humidity — RH5~95%, non-condensed

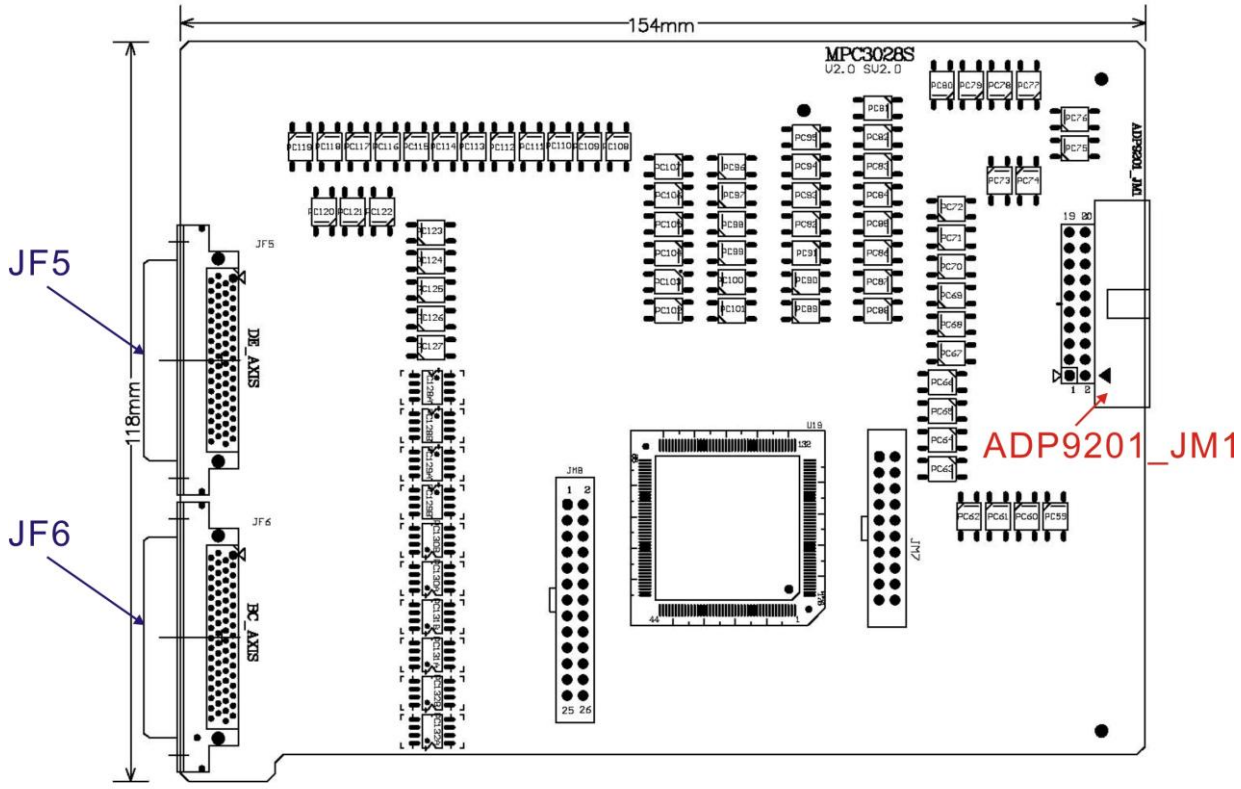
3.2.18 Dimension — ADP9201DIN(R) / (P) : 86(W) * 103(L) *45(H)mm;
3.4(W)*4.1(L)*1.8(H)in
ADP9201DIN(S) : 86(W) * 103(L) *50(H)mm
3.4(W)*4.1(L)*2.0(H)in

4. Layout and dimension

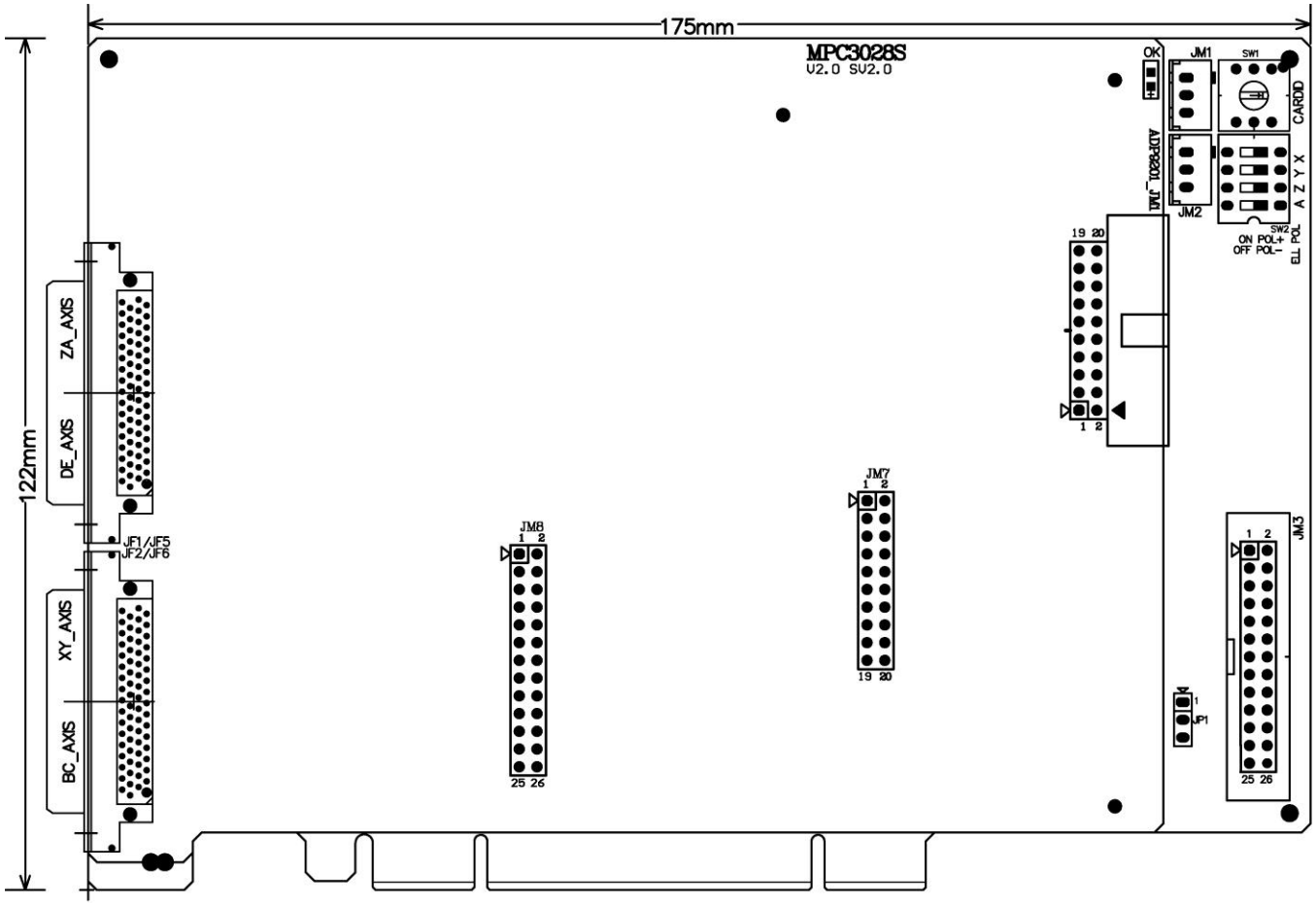
4.1 MPC3028A Main card



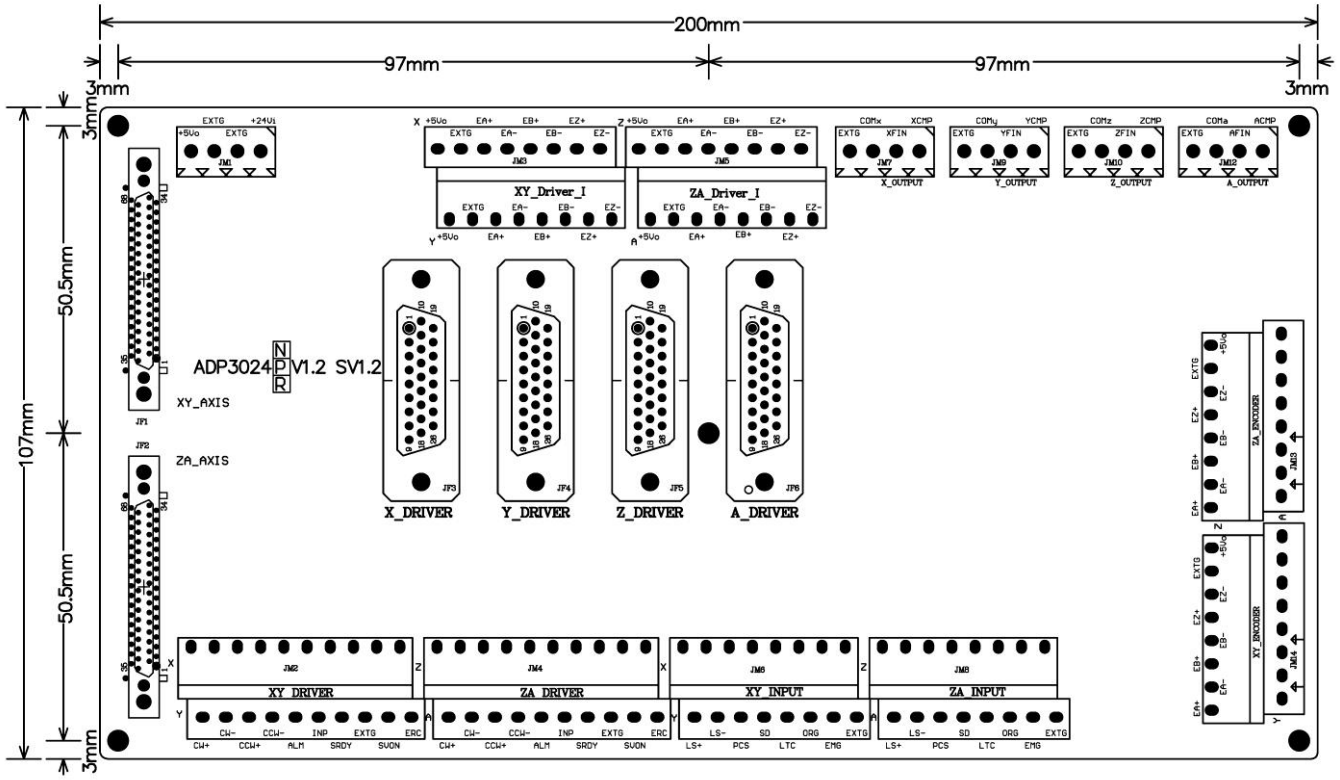
4.2 MPC3028A daughter card



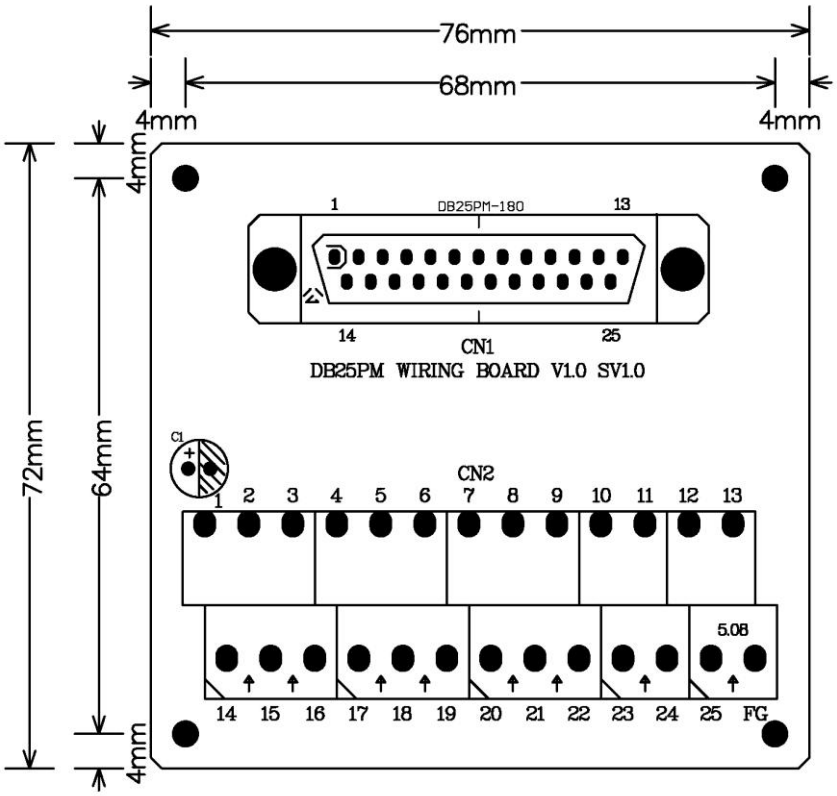
4.3 MPC3028A piggy back



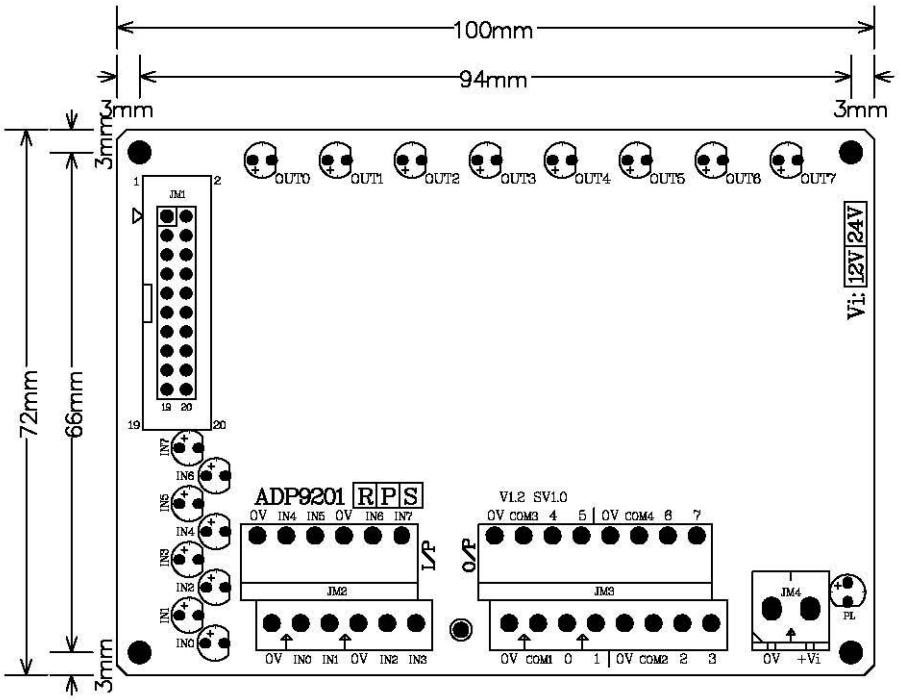
4.4 ADP3024DIN for JF1,2,5,6 Din rail mounted wiring board



4.5 JS51050 for JM3 25PM Din rail mounted dummy wiring board

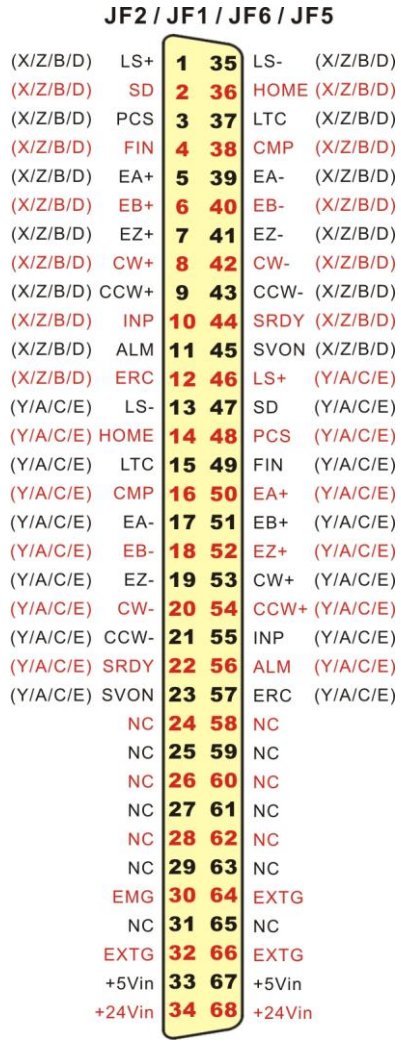


4.6 ADP9201DIN for ADP9201_JM1 Din rail mounted wiring board



5. Pin definitions

5.1 JF1,JF2,JF5,JF6 Assignment / Definitions



JF2: for X,Y axis

JF1: for Z,A axis

JF6: for B,C axis

JF5: for D,E axis

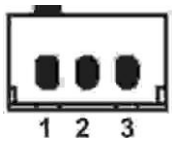
Note: Be sure the wiring board is power off for more than 1min while to connect or disconnect the cable.

PIN	I/O	Descriptions
1	I	X/Z/B/D_LS+(EL+) Positive over travel LS(EL) of X/Z/B/D axis
2	I	X/Z/B/D_SD Slowdown LS(EL) of X/Z/B/D axis
3	I	X/Z/B/D_PCS Position change start signal of X/Z/B/D axis
4	O	X/Z/B/D_FIN General purpose output of X/Z/B/D axis
5	I	X/Z/B/D_EA+ Encoder phase A+ feedback of X/Z/B/D axis
6	I	X/Z/B/D_EB+ Encoder phase B+ feedback of X/Z/B/D axis
7	I	X/Z/B/D_EZ+ Encoder phase Z+ feedback of X/Z/B/D axis
8	O	X/Z/B/D_CW+ CW+ or PULSE+ of X/Z/B/D axis
9	O	X/Z/B/D_CCW+ CCW+ or DIR+ of X/Z/B/D axis
10	I	X/Z/B/D_INP General I/p of X/Z/B/D axis
11	I	X/Z/B/DALM ALARM I/p of X/Z/B/D axis
12	O	X/Z/B/D_ERC Output for resetting error counter of X/Z/B/D axis
13	I	Y/A/C/E_LS-(EL-) Negative over travel LS(EL) of Y/A/C/E axis
14	I	Y/A/C/E_HOME(ORG) Home(ORG) LS(EL) of Y/A/C/E axis
15	I	Y/A/C/E_LTC Latch counter trigger of Y/A/C/E axis
16	O	Y/A/C/E_CMP General out or compare out of Y/A/C/E axis
17	I	Y/A/C/E_EA- Encoder phase A- feedback of Y/A/C/E axis
18	I	Y/A/C/E_EB- Encoder phase B- feedback of Y/A/C/E axis
19	I	Y/A/C/E_EZ- Encoder phase Z- feedback of Y/A/C/E axis
20	O	Y/A/C/E_CW- CW- or PULSE- of Y/A/C/E axis
21	O	Y/A/C/E_CCW- CCW- or DIR- of Y/A/C/E axis
22	I	Y/A/C/E_SRDY Servo Ready signal of Y/A/C/E axis
23	O	Y/A/C/E_SVON Servo on of Y/A/C/E axis
24 | 29		NC
30	I	EMG Emergency stop, stop all axes
31		NC
32		EXTG Common for external power (+24V and +5V)
33	O	+5V DC5V power output for external device
34	I	+24V External DC24V power input

PIN	I/O	Descriptions
35	I	X/Z/B/D_LS-(EL-) Negative over travel LS(EL) of X/Z/B/D axis
36	I	X/Z/B/D_HOME(ORG) Home(ORG) LS(EL) of X/Z/B/D axis
37	I	X/Z/B/D_LTC Latch counter trigger of X/Z/B/D axis
38	O	X/Z/B/D_CMP General out or compare out of X/Z/B/D axis
39	I	X/Z/B/D_EA- Encoder phase A- feedback of X/Z/B/D axis
40	I	X/Z/B/D_EB- Encoder phase B- feedback of X/Z/B/D axis
41	I	X/Z/B/D_EZ- Encoder phase Z- feedback of X/Z/B/D axis
42	O	X/Z/B/D_CW- CW- or PULSE- of X/Z/B/D axis
43	O	X/Z/B/D_CCW- CCW- or DIR- of X/Z/B/D axis
44	I	X/Z/B/D_SRDY Servo Ready signal of X/Z/B/D axis
45	O	X/Z/B/D_SVON -- Servo on of X/Z/B/D axis
46	I	Y/A/C/E_LS+(EL+) Positive over travel LS(EL) of Y/A/C/E axis
47	I	Y/A/C/E_SD Slowdown LS(EL) of Y/A/C/E axis
48	I	Y/A/C/E_PCS Position change start signal of Y/A/C/E axis
49	O	Y/A/C/E_FIN General purpose output of Y/A/C/E axis
50	I	Y/A/C/E_EA+ Encoder phase A+ feedback of Y/A/C/E axis
51	I	Y/A/C/E_EB+ Encoder phase B+ feedback of Y/A/C/E axis
52	I	Y/A/C/E_EZ+ Encoder phase Z+ feedback of Y/A/C/E axis
53	O	Y/A/C/ECW+ CW+ or PULSE+ of Y/A/C/E axis
54	O	Y/A/C/E_CCW+ CCW+ or DIR+ of Y/A/C/E axis
55	I	Y/A/C/E_INP General I/p of Y/A/C/E axis
56	I	Y/A/C/E_ALM ALARM I/p of Y/A/C/E axis
57	O	Y/A/C/E_ERC Output for resetting error counter of Y/A/C/E axis
58 | 63		NC
64		EXTG Common for external power (+24V and +5V)
65		NC
66		EXTG Common for external power (+24V and +5V)
67	O	+5V DC5V power output for external device
68	I	+24V External DC24V power input

5.2 JM1,JM2 Assignment / Definitions

PIN	Description
1	CSTA: common start I/O
2	CSTP: common stop I/O
3	GND

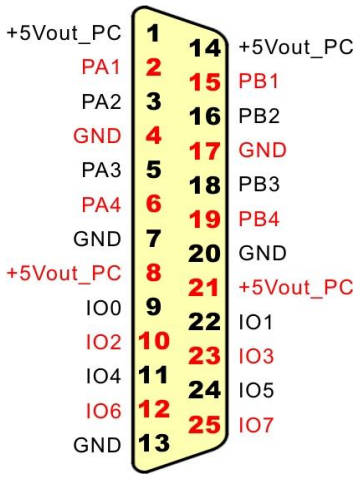


Note: Connect CSTA low to start motion from external.

Connect CSTP low to emergency stop motion from external.

5.3 JM3 Assignment / Definitions

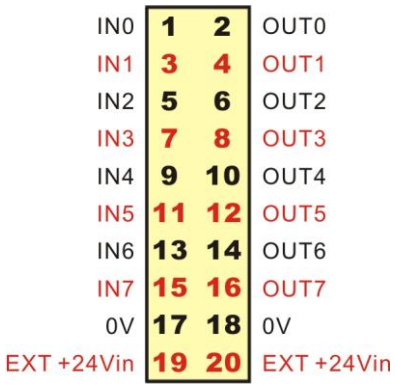
PIN	Description
1	+5Vout_PC +5V from PC
2	PA1 Pulse handler1 A phase input
3	PA2 Pulse handler2 A phase input
4	GND
5	PA3 Pulse handler3 A phase input
6	PA4 Pulse handler4 A phase input
7	GND
8	+5Vout_PC +5V from PC
9	IO0 TTL I/O bit0
10	IO 2 TTL I/O bit2
11	IO 4 TTL I/O bit4
12	IO 6 TTL I/O bit6
13	GND



PIN	Description
14	+5Vout_PC +5V from PC
15	PB1 Pulse handler1 B phase input
16	PB2 Pulse handler2 B phase input
17	GND
18	PB3 Pulse handler3 B phase input
19	PB4 Pulse handler4 B phase input
20	GND
21	+5Vout_PC +5V from PC
22	IO1 TTL I/O bit1
23	IO 3 TTL I/O bit3
24	IO 5 TTL I/O bit5
25	IO 7 TTL I/O bit7

5.4 ADP9201_JM1 Assignment / Definitions

PIN	Description
1	IN0: Isolated I/P 0
3	IN1: Isolated I/P 1
5	IN2: Isolated I/P 2
7	IN3: Isolated I/P 3
9	IN4: Isolated I/P 4
11	IN5: Isolated I/P 5
13	IN6: Isolated I/P 6
15	IN7: Isolated I/P 7
17	0V: External GND
19	24V: External +24Vdc



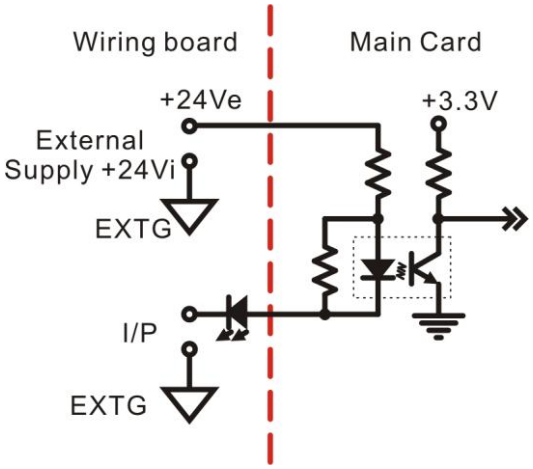
PIN	Description
2	OUT0: Isolateds O/P 0
4	OUT1: Isolateds O/P 1
6	OUT2: Isolateds O/P 2
8	OUT3: Isolateds O/P 3
10	OUT4: Isolateds O/P 4
12	OUT5: Isolateds O/P 5
14	OUT6: Isolateds O/P 6
16	OUT7: Isolateds O/P 7
18	0V: External GND
20	24V: External +24Vdc

6. I/O interface diagram

6.1 JF1/2 ADP3024DIN

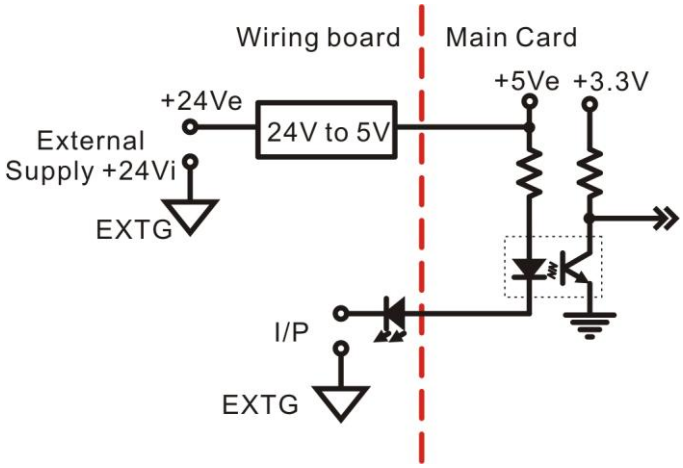
6.1.1 Input diagram

Type1 input:



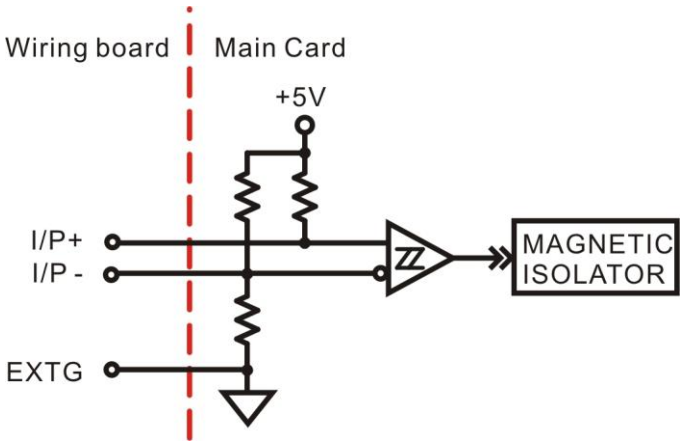
For input: LS+(EL+), LS-(EL-), HOME(ORG), SD,PCS,EMG, LTC

Type2 input:



For input: INP,SRDY,ALM

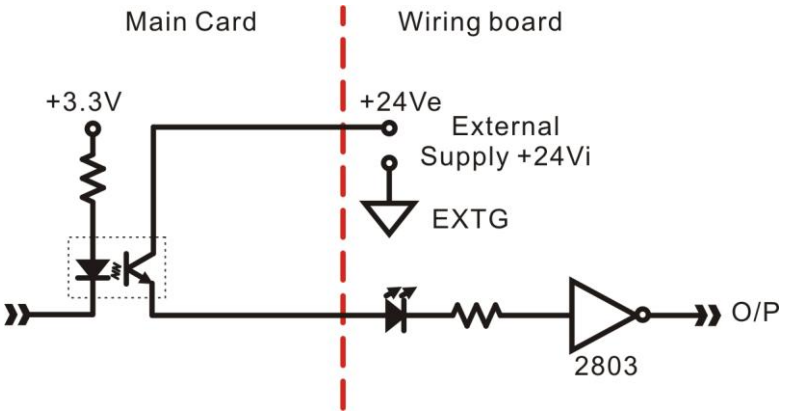
Type3 input:



For encoder feedback input : A+/-,B+/-,Z/-

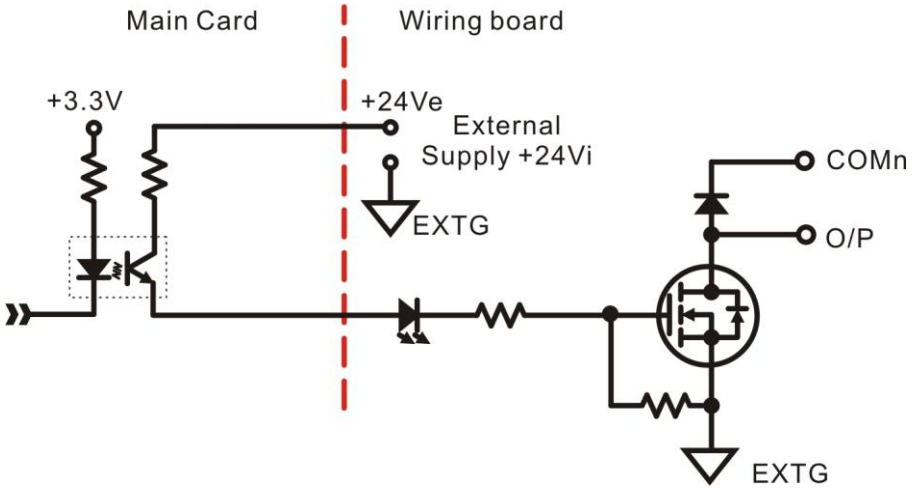
6.1.2 Output diagram

Type1 output:



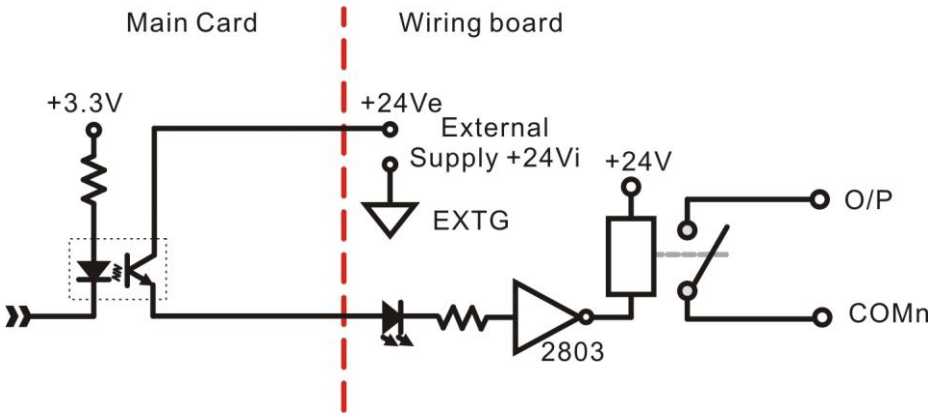
For SVON, ERC

Type2 output:



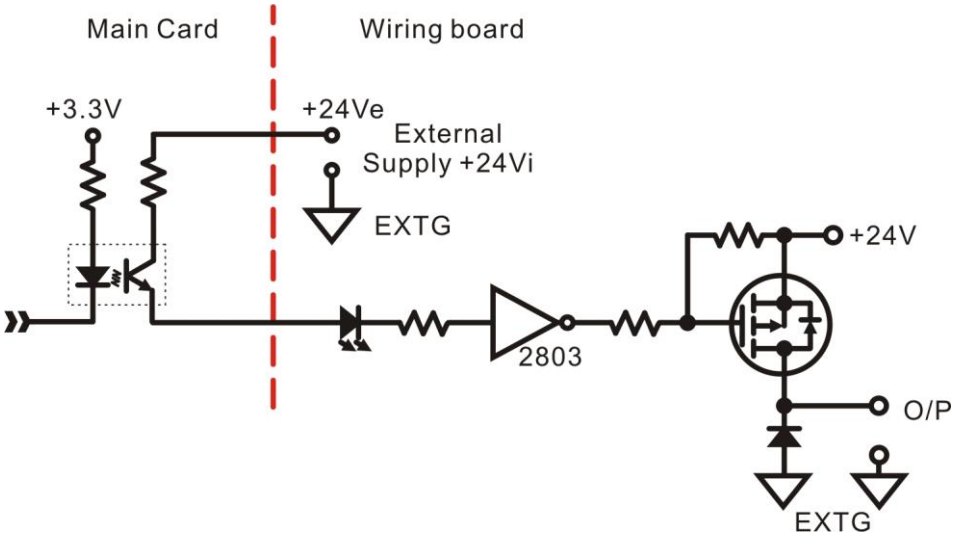
FIN,CMP(NMOS)

Type3 output:



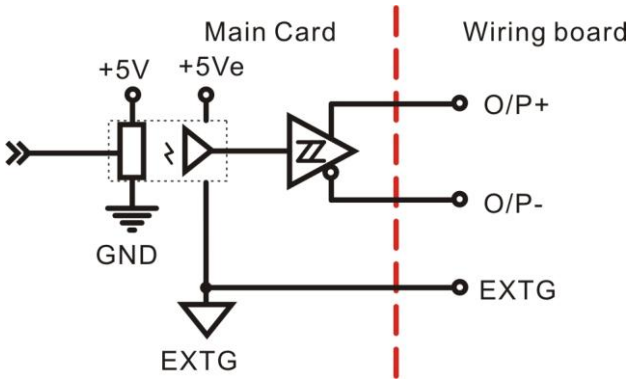
FIN,CMP(Relay)

Type4 output:



FIN,CMP(PMOS)

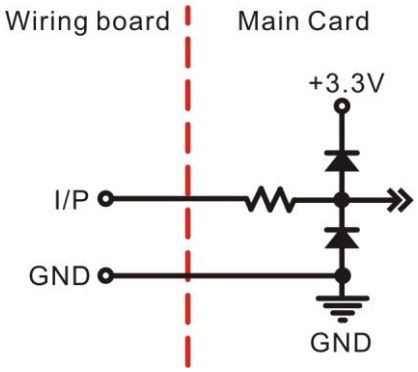
Type5 output:



For motion control pulse output : CW,CCW

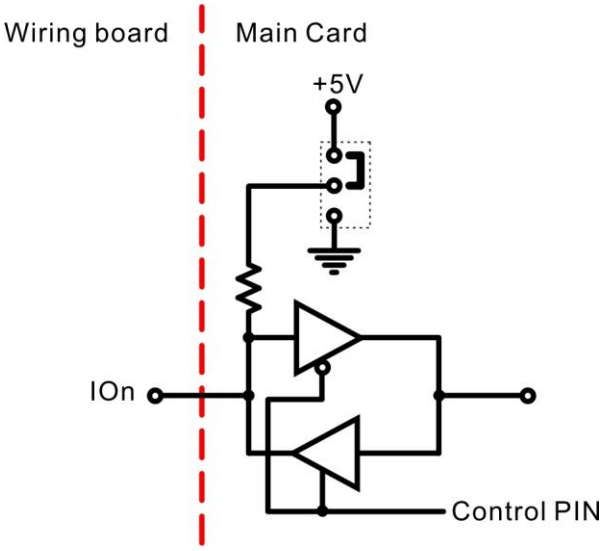
6.2 JM3 JS51050

Type 1 Input:



For Pulse Handler Input : PA,PB

Type 2 TTL I/O:

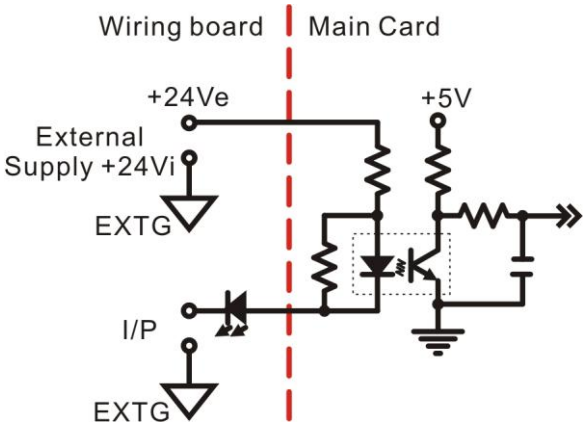


For byte-programmable TTL I/O IO0 ~ IO7 to configured as pull high or pull low. JP1 are used for output state of power on. (refer 8.3 JP1 Jumper setting)

6.3 ADP9201_JM1 ADP9201DIN

6.3.1 Input diagram

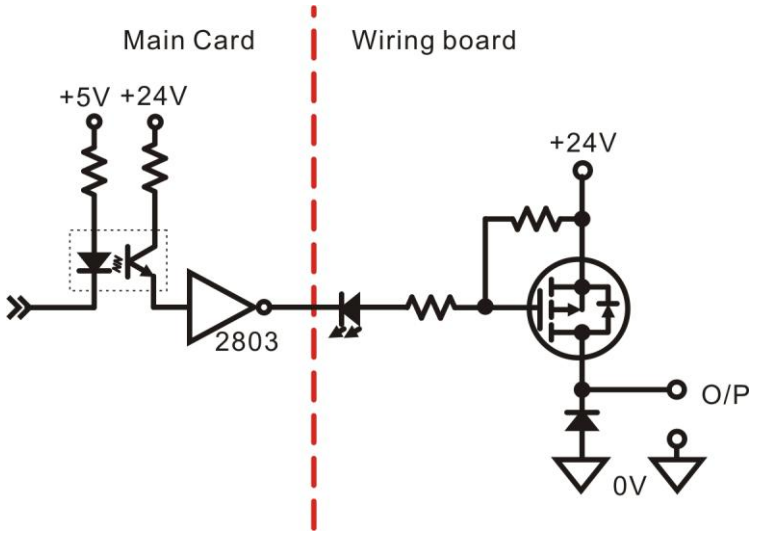
Type 1 Input:



For IN0~IN7

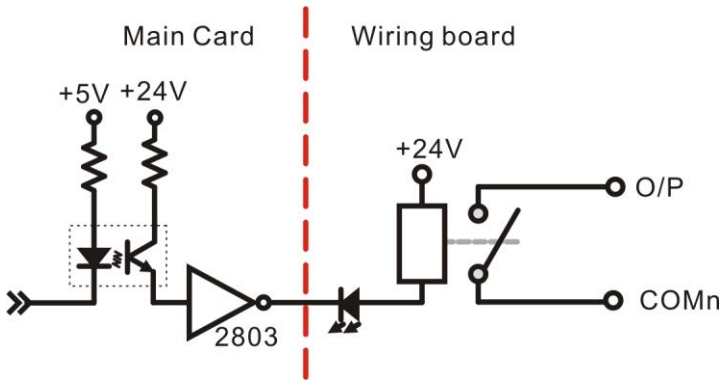
6.3.2 Output diagram

Type 1 output : (PMOS)



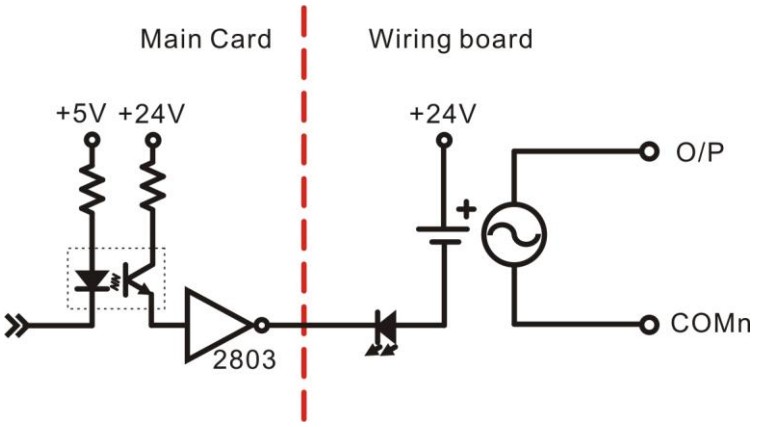
For OUT0~OUT7

Type 2 output : (Relay)



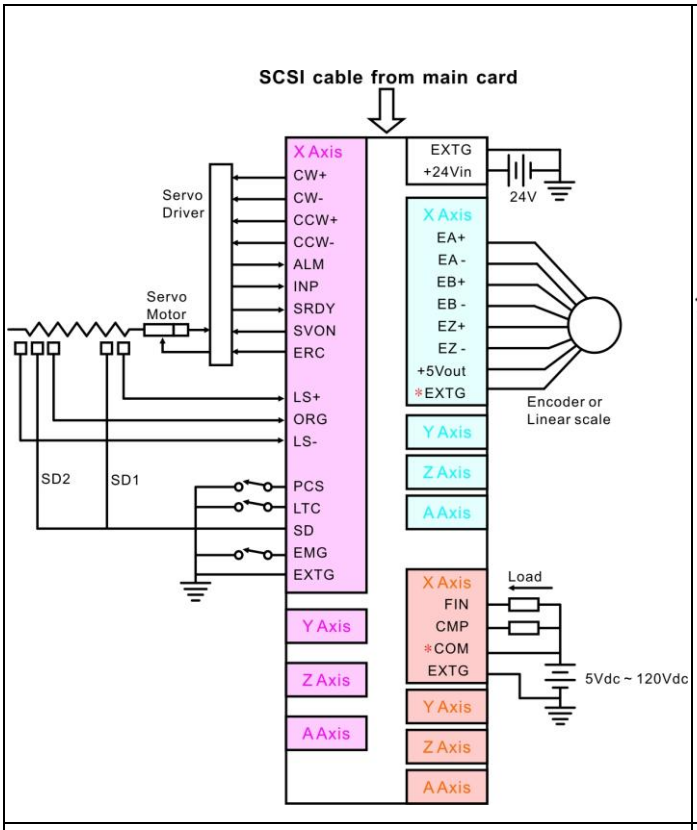
For OUT0~OUT7

Type 3 output : (SSR)

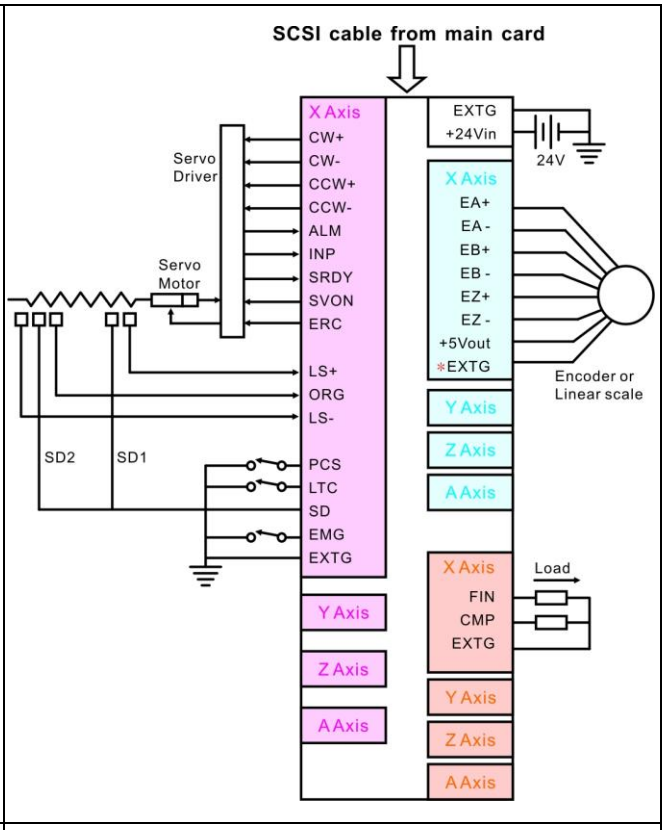


For OUT0~OUT7

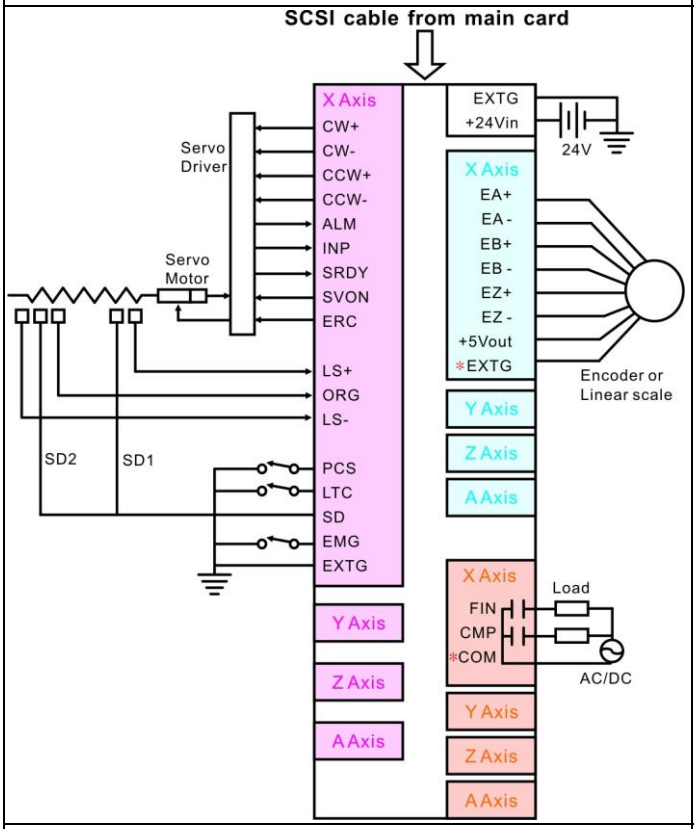
7. External wiring diagram



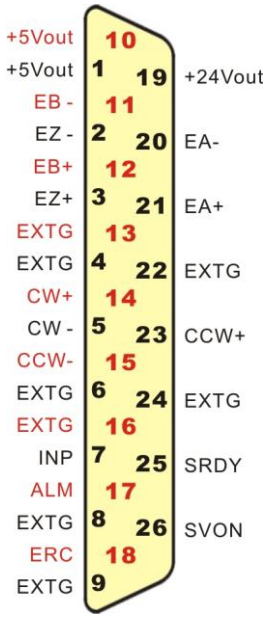
wiring board with NMOS output



wiring board with PMOS output



Wiring board with Relay output



* User may connect the signals with this DB26 specific connectors (one axis per connector) or screw terminals.

Wiring board DB26 specific connector

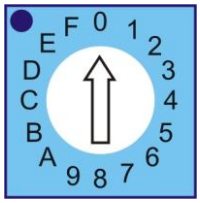
*Differential signals needs connect EXTG as common.

*COM connect to power supply as free-wheel path to avoid high voltage induced by inductive load.

8. Hardware settings

8.1 Card ID setting

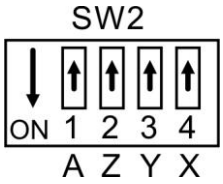
Since PCI cards have plug and play function, the card ID is required for programmer to identify which card he/she will control without knowing the physical address assigned by the Windows. A 4 bits ROTARY switch (select from 0 to 0xF)for extinguishing the 16 identical card.



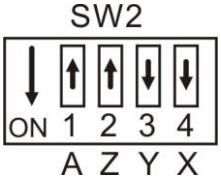
8.2 Polarity setting for over-travel limit switch

For different applications maybe you have different considerations, the polarity of over-travel limit switch can be set by on card Dip switch to meet your requirement.

Default : A, Z, Y, X axis are in negative polarity , the DIP switch set as follows.



Example : A, Z axis are in negative polarity and Y, X axis polarity are positive, the DIP switch set as follows.



8.3 JP1 Jumper setting

	
1-2 short Pull High	2-3 short Pull Low

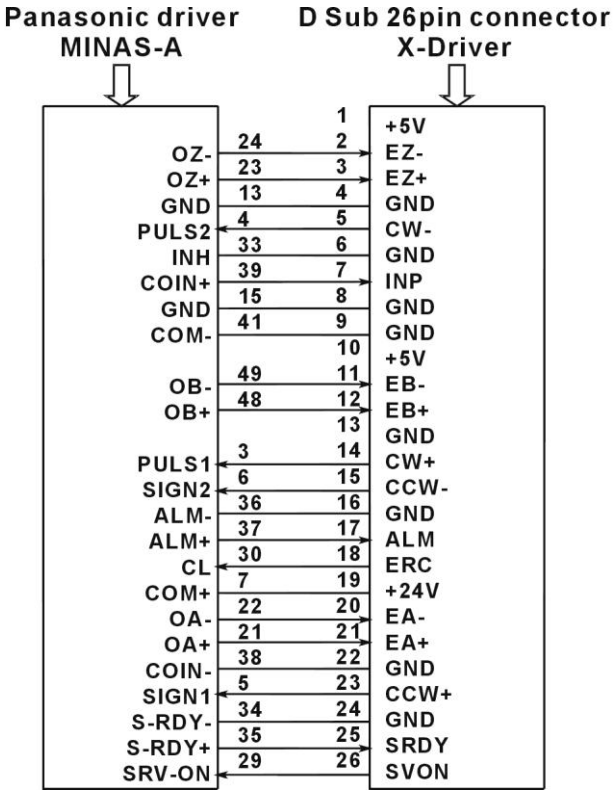
Jumper JP1 is used for the TTL output default state, if you disable the TTL port or at computer start-up period, the default state will be output. Select the one to match with the succeeding circuit.

9. Applications

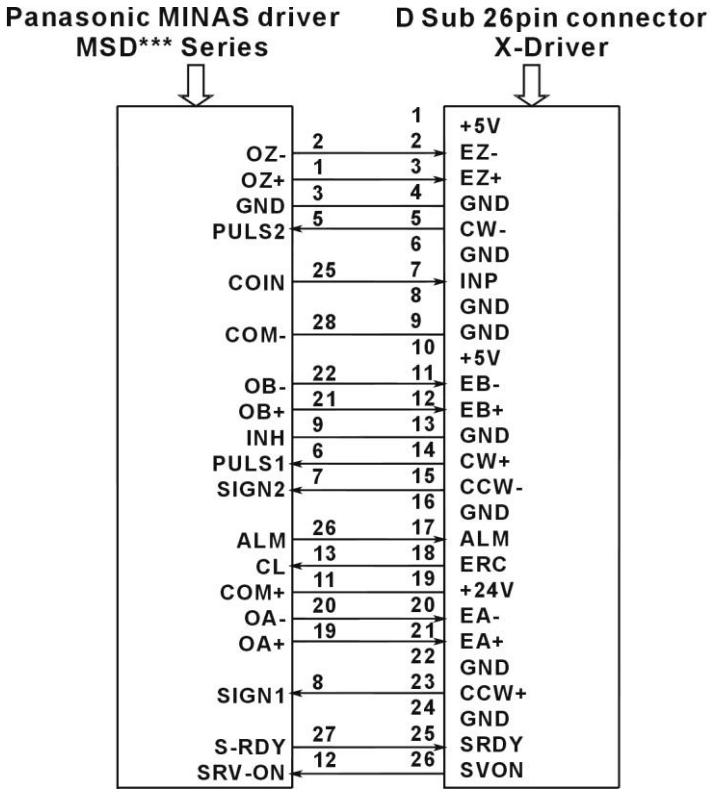
- Precision positioning control
- Precision speed control
- Contouring control
- X-Y table control
- Rotary machine control
- Robotic control
- Biotech sampling and handling
- Any combined control of servo and stepping motors

10. Wiring diagram examples

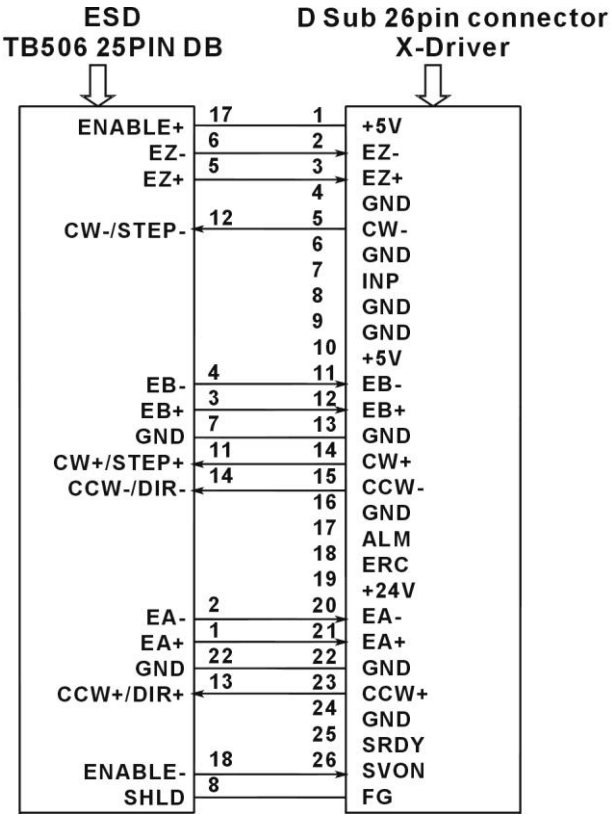
10.1 The wiring diagram for MPC3028A wiring board to panasonic MINAS-A driver



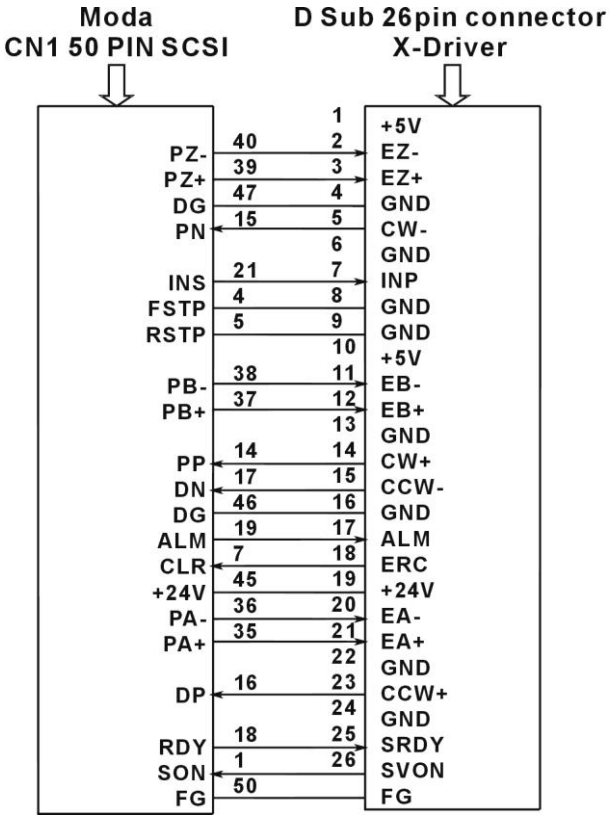
10.2 The wiring diagram for MPC3028A wiring board to panasonic MINAS MSD*** driver



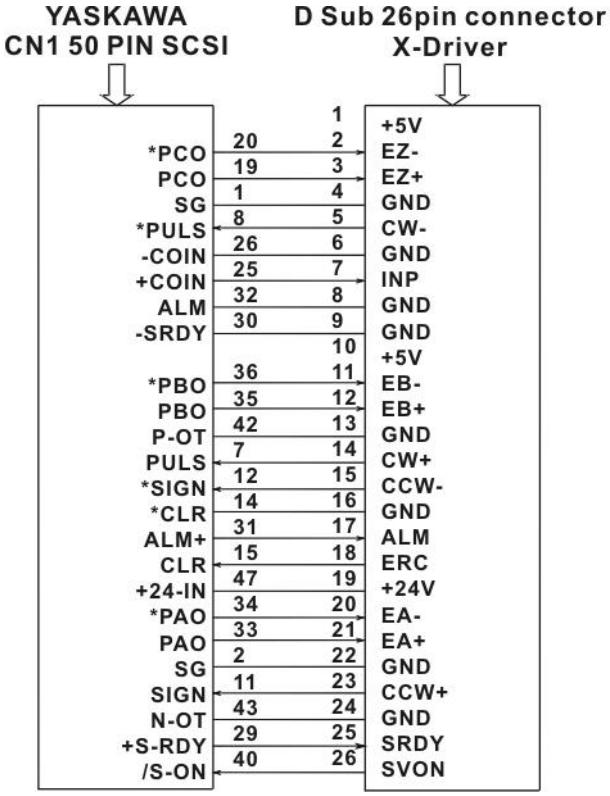
10.3 The wiring diagram for MPC3028A wiring board to ESD servo driver



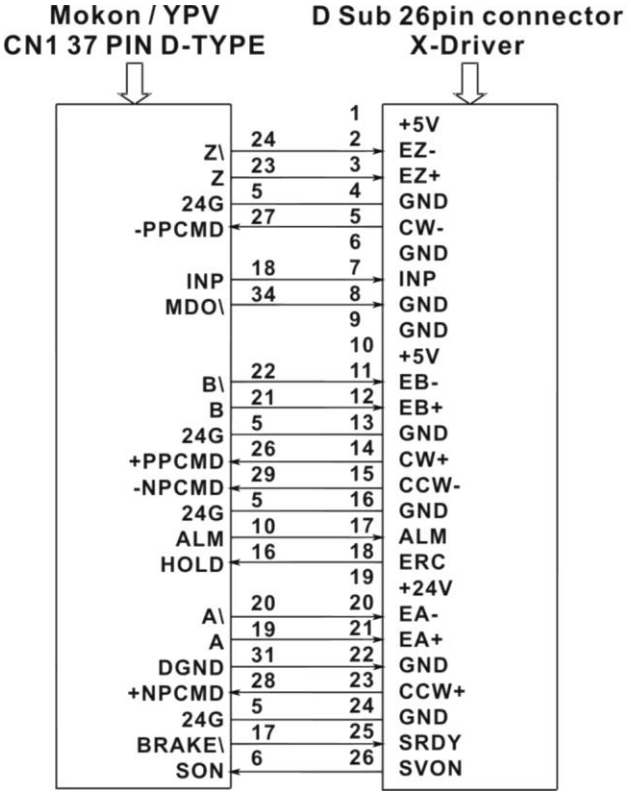
10.4 The wiring diagram for MPC3028A wiring board to Moda servo driver



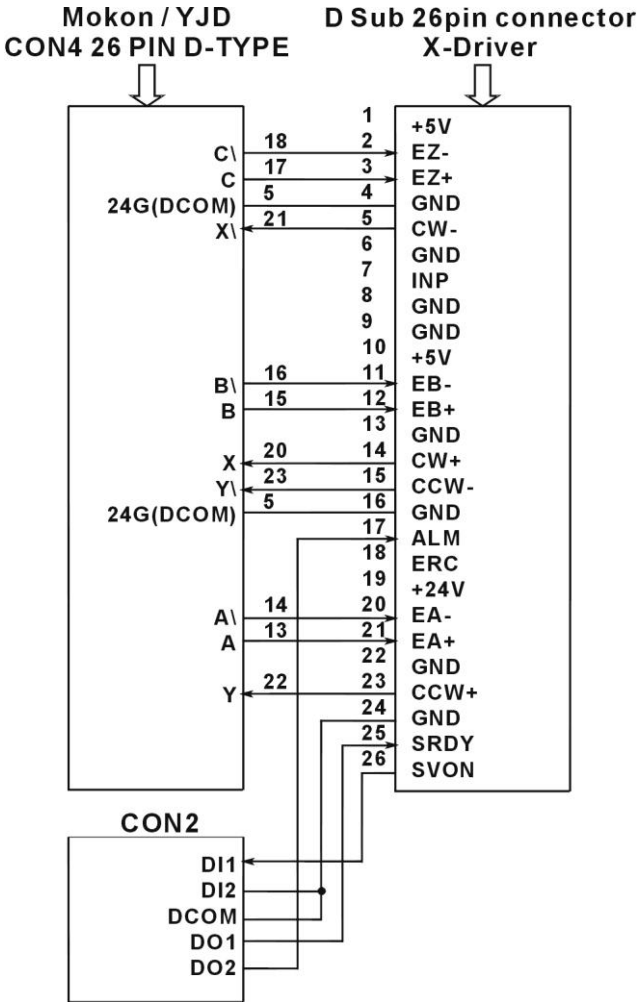
10.5 The wiring diagram for MPC3028A wiring board to YASKAWA servo driver



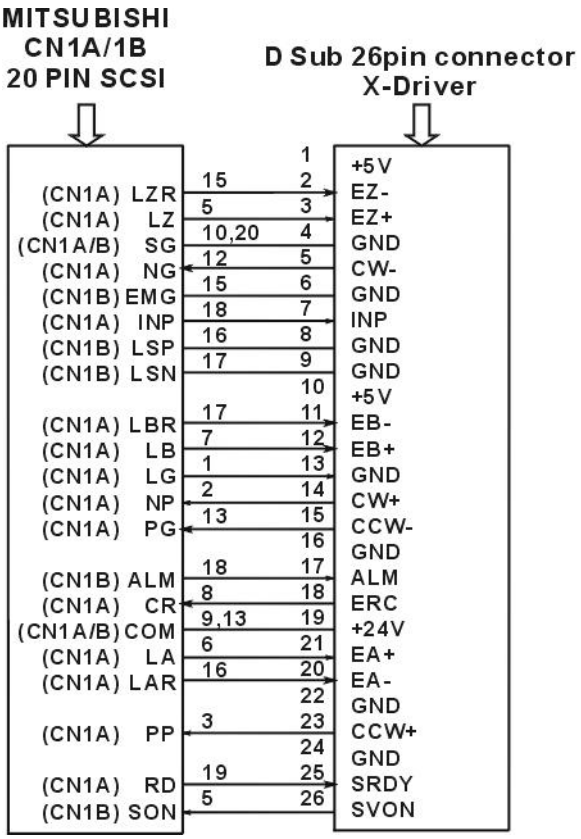
10.6 The wiring diagram for MPC3028A wiring board to Mokon / YPV servo driver



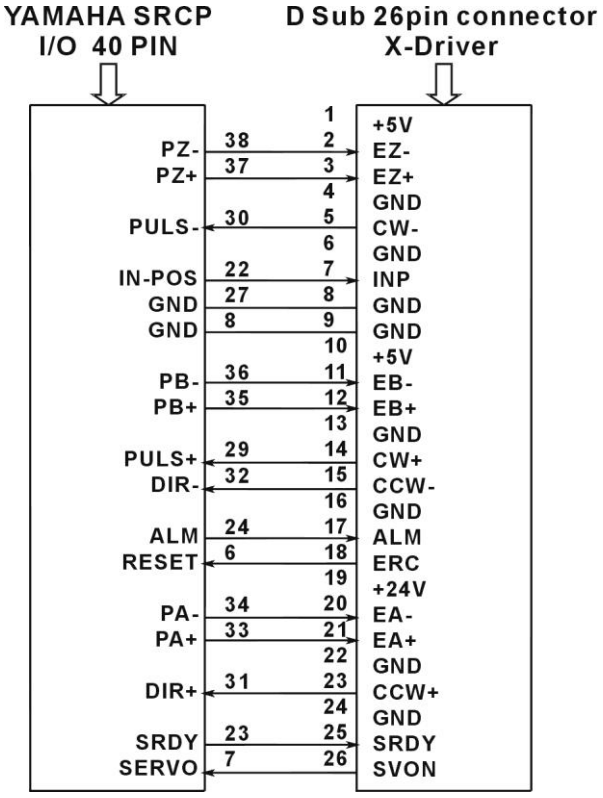
10.7 The wiring diagram for MPC3028A wiring board to Mokon / YJD servo driver



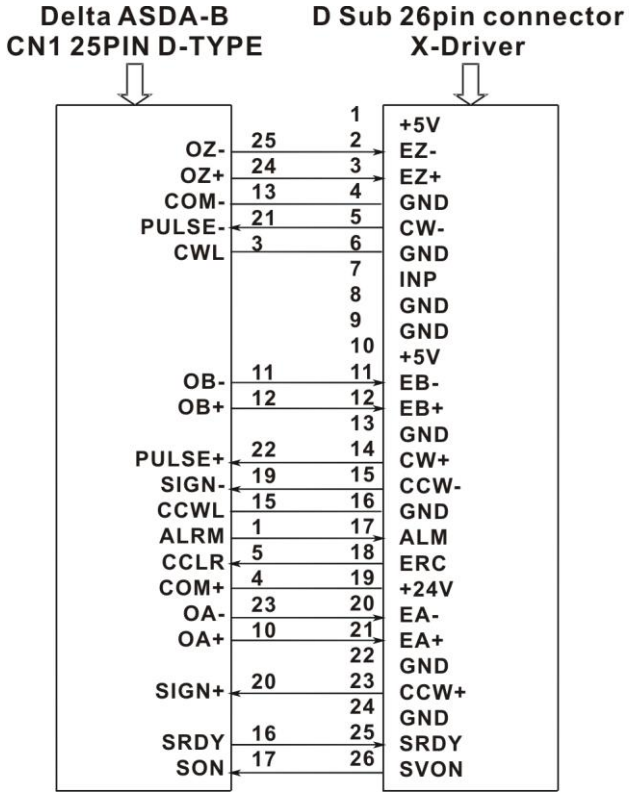
10.8 The wiring diagram for MPC3028A wiring board to MITSUBISHI J2-SUPER servo driver



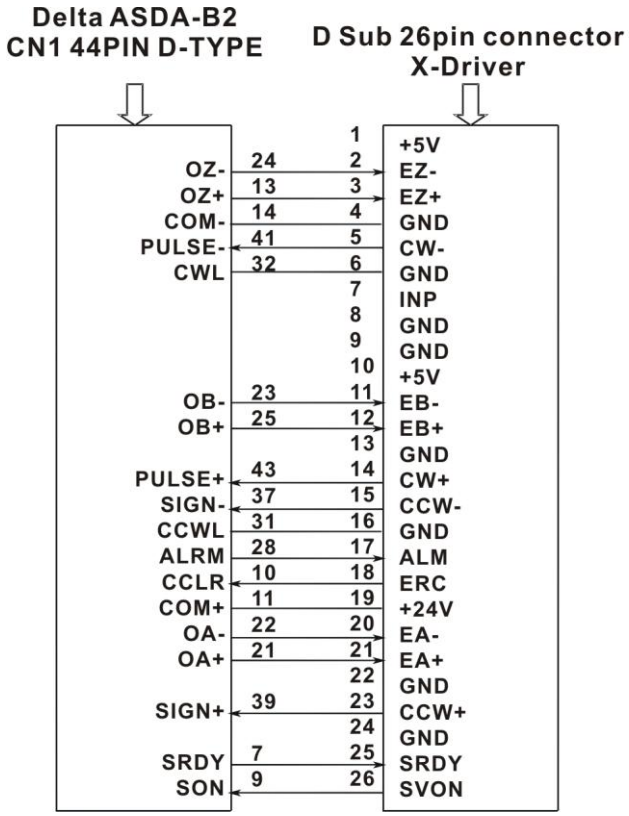
10.9 The wiring diagram for MPC3028A wiring board to YAMAHA SRCP servo driver



10.10 The wiring diagram for MPC3028A wiring board to Delta ASDA-B servo driver



10.11 The wiring diagram for MPC3028A wiring board to Delta ASDA-B2 servo driver



11. Ordering information

PRODUCT	DESCRIPTIONS
MPC3028A	8-axis motion control card for servo/step motor control
ADP3024DIN(N)	DIN rail mounted wiring board matched MPC3024/3028/3034/3035/3035L/3024A/3028A/3034A/3035A/3035AL, General output: 8 power NMOS
ADP3024DIN(P)	DIN rail mounted wiring board matched MPC3024/3028/3034/3035/3035L/3024A/3028A/3034A/3035A/3035AL, General output: 8 power PMOS
ADP3024DIN(R)	DIN rail mounted wiring board matched MPC3024/3028/3034/3035/3035L/3024A/3028A/3034A/3035A/3035AL, General output: 8 relays
JS51050	DIN rail mounted dummy wiring board for JM3
ADP9201DIN(R)	DIN rail mounted wiring board with 16 I/O LED indicators and relay output for 8DI, 8DO (for ADP9201_JM1)
ADP9201DIN(P)	DIN rail mounted wiring board with 16 I/O LED indicators and PMOS output for 8DI, 8DO (for ADP9201_JM1)
ADP9201DIN(S)	DIN rail mounted wiring board with 16 I/O LED indicators and SSR output for 8DI, 8DO (for ADP9201_JM1)
FVC01	F to V Module
M266868151	68-pin mini-SCSI cable 1.5M (2 axes control signal granted in one cable)
M2668683011	68-pin mini-SCSI cable 3.0M (2 axes control signal granted in one cable)
M270325X4	D type 25p male-female cable 1.5M
M270325X4S	D type 25p male-female cable 1.5M,shielding
M270325X0	D type 25p male-female cable 3.0M
M270325X0S	D type 25p male-female cable 3.0M,shielding
M23207	20p flat cable 1.5M
M23209	20p flat cable 3.0M
SM23404	Extension kit for JM3 (bracket and flat cable for 25p D-type connector)